

Amendments to the Claims:

- 1 1. (currently amended) A lift truck, load stabilization system for controlling ~~the tilt~~
2 ~~angle of a lifting lift~~ mast ~~tilt angle, the mast~~ having a cargo support mounted to the
3 mast and a tilt actuator for adjusting the mast tilt angle relative to the lift truck ~~frame~~,
4 the system comprising:
- 5 a. an acceleration sensor mounted to the lift truck for sensing an the angular
6 direction of a resultant of the forces of gravitational acceleration and vehicle
7 travel acceleration; and
- 8 b. a negative feedback control system having
- 9 i. a feedback element input connected to the acceleration sensor for
10 feedback of said resultant angular direction,
- 11 ii. a reference input storage for storing a value of angular direction
12 representing the resultant angular direction of acceleration when the
13 lift truck is at rest and the cargo support is horizontal; and
- 14 iii. an output connected to control said actuator for controllably varying
15 the mast tilt angle and bringing the resultant angular direction into
16 alignment with the stored reference angular direction.

- 1 2. (original) A lift truck system in accordance with claim 1 wherein the tilt actuator
2 includes at least one double acting hydraulic cylinder actuator hydraulically connected to
3 a bidirectional, proportional, hydraulic valve for controlling the hydraulic fluid flow to

4 the tilt actuator, the hydraulic valve having a control input linked to the output of the
5 negative feedback control system for controlling the actuator to tilt the mast to a tilt angle
6 within a smoothly continuous tilt angle range.

1 3. **(withdrawn)** A lift truck system in accordance with claim 2 wherein the control
2 system comprises an analog proportional controller.

1 4. **(original)** A lift truck system in accordance with claim 2 wherein the control system
2 comprises is a PID controller.

1 5. **(original)** A lift truck system in accordance with claim 2 wherein the hydraulic valve
2 is electrically actuated.

1 6. **(withdrawn)** A method for adjusting the tilt angle of the load supporting surface
2 of a lift truck, the method comprising: adjusting the tilt angle of the load supporting
3 surface during lift truck operation to maintain the load supporting surface substantially
4 perpendicular to the angular direction of the resultant of gravitational and travel
5 acceleration.

1 7. **(withdrawn)** A method for adjusting the tilt angle of the load supporting surface of a
2 lift truck, the method comprising:

- 3 a. storing the angular direction of gravitational acceleration upon the load
4 supporting surface when the lift truck is at rest and the load supporting surface
5 is substantially horizontal;
6 b. sensing the resultant angular direction of gravitational and travel acceleration
7 during lift truck operation; and
8 c. tilting the load supporting surface through the angular difference of said
9 angular directions to align the load supporting surface substantially
10 perpendicular to the resultant angular direction.

- 1 8. (withdrawn) A method in accordance with claim 7 wherein the storing step is
2 performed by positioning the lift truck at rest with the load supporting surface
3 substantially horizontal and storing a sensed angular direction of gravitational force.